

Gaussian Mixture Model Phonetics

LING 492B

Motivation: Phonetic Distributions

- Formants: resonant frequencies (Hz)
 - Vocal tract
 shape
 e.g. F1, F2
- Acoustic cue to vowel category









Inspired by Pierrehumbert (2001)



Approximating with Gaussians



Gaussian distributions

Parameters: Mean (mu or µ)

$\sum_{i}^{N} p(X_i) X_i$



Gaussian distributions

Parameters: Mean (µ)

Variance (σ^2): average spread from mean

 $\sum_{i}^{N} p(X_i)(X_i - \mu)^2$



Relative Likelihood





Mixture of Gaussians Parameters



GMM Categorization

Did I hear "pin" or "pen"?

x = 2300Hz

We want: P([I] | x=2300) P([ɛ] | x=2300)



 $P([\varepsilon] | x) = P(x | [\varepsilon]) P([\varepsilon]) / P(x)$

P([I] | x) = P(x | [I])P([I])/P(x)

Bayes again! P(A|B) = P(B|A)P(A)/P(B)



Bayes again! P([I] | x) =P(x | [I])P([I])/P(x) = $N(x | \mu_{I'} \sigma_{I}^2) * P([I])/P(x) =$ 0.0012 / P(x)



 $\mu_{I} = 2400$ $\sigma_{I}^{2} = 100$ P([I]) = 0.5x = 2300 Bayes again!

 $P([\varepsilon] | x) =$ $P(x | [\varepsilon]) P([\varepsilon]) / P(x) =$ $N(x | \mu_{\varepsilon}, \sigma_{\varepsilon}^{2}) * P([\varepsilon]) / P(x) =$ 0.00060 / P(x)



$$\mu_{\epsilon} = 2100$$

 $\sigma_{\epsilon}^{2} = 180$
 $P([\epsilon]) = 0.5$
 $x = 2300$

$P([I] | x) > P([\varepsilon] | x)$

 $P([\epsilon] | x) = 0.00060/0.00060 + 0.0012 = .33$ P([I] | x) = 0.0012/0.00060 + 0.0012 = .67

 $P([\epsilon] | x) = 0.00060/P(x)$ P([I] | x) = 0.0012/P(x)

Bayes again!



Estimating GMM parameters: labeled data



Estimating parameters: Labeled Data

[I]: 2600Hz
[ɛ]: 2200Hz
[I]: 2500Hz
[ɛ]:1600Hz
[I]: 2300Hz
[I]: 2100Hz





[I]: 2600Hz
[ε]: 2200Hz
[Ι]: 2500Hz
[ε]: 1600Hz
[Ι]: 2300Hz
[Ι]: 2100Hz

μ₁= 2375 $\sigma_{1}^{2} = \dot{s}$ i = ³μ $\sigma^2 = \dot{s}$ **?** =(3) P(€) P(I)= ?



[I]: 2600Hz
[ε]: 2200Hz
[Ι]: 2500Hz
[ε]: 1600Hz
[Ι]: 2300Hz
[Ι]: 2100Hz

µ_= 2375 **σ**²_τ= 221 h^ε= š $\sigma^2 = \dot{s}$? = (3) P $\mathsf{b}(\mathbf{I}) = \mathbf{i}$



[I]: 2600Hz
[ε]: 2200Hz
[Ι]: 2500Hz
[ε]: 1600Hz
[Ι]: 2300Hz
[Ι]: 2100Hz

µ_= 2375 $\sigma^{2}_{T} = 221$ $\mu_{e} = 1900$ $\sigma_{\epsilon}^2 = \dot{s}$ **?** =(3) P(€) P(I)= \$



[I]: 2600Hz
[ε]: 2200Hz
[Ι]: 2500Hz
[ε]: 1600Hz
[Ι]: 2300Hz
[Ι]: 2100Hz

µ_= 2375 $\sigma^{2} = 221$ $\mu_{e} = 1900$ $\sigma_{e}^{2} = 424$? = (3) P P(**I**)= 5



[I]: 2600Hz
[ε]: 2200Hz
[Ι]: 2500Hz
[ε]: 1600Hz
[Ι]: 2300Hz
[Ι]: 2100Hz

µ_= 2375 $\sigma_{T}^{2} = 221$ $\mu_{e} = 1900$ $\sigma_{\epsilon}^2 = 424$ $P(\varepsilon) = 2/6$ P(I) =



[I]: 2600Hz
[ε]: 2200Hz
[Ι]: 2500Hz
[ε]: 1600Hz
[Ι]: 2300Hz
[Ι]: 2100Hz

µ_= 2375 $\sigma_{T}^{2} = 221$ μ_ε= 1900 $\sigma_{\epsilon}^2 = 424$ $P(\varepsilon) = 2/6$ P(I) = 4/6



Task #2: Unsupervised Learning

What are the categories? What are their parameters (µ, σ,π)?



Unsupervised learning: cognition

How do infants learn phoneme categories with so much overlap? [Feldman 2009, Vallabha 2007]

Without knowing anything about the categories beforehand, input data looks like this:



GMM Expectation-Maximization

Intuition:

- If we knew the vowel labels, we could estimate mu and sigma for each category
 - But we don't know the vowel labels :(

- If we knew mu and sigma for each category, we could estimate the vowel labels
 - But we don't know the mus and sigmas :(

GMM Expectation-Maximization

Initialization: Start with k categories with random means and variances [cf. k-means!]



Based on demo from Victor Lavrenko

GMM Expectation-Maximization

Expectation: How likely is each category for each label?



GMM Expectation

Expectation: How likely is each category for each label?

For each observation **x**, for each category c (μ_c , σ_c^2), compute: **P(c|x)** = N(x | μ_c , σ^2) * P(c)/P(x)

000Hz 1500Hz

GMM Expectation

Expectation: How likely is each category for each label? For each observation **x**, for each category **c** ($\mu_{c'}$, σ_{c}^{2}), compute:

$$P(c | x) = N(x | \mu_{c'} \sigma^2) * P(c)/P(x)$$

cf. k-means: *soft* categorization



Maximization: Update each category's parameters based on the observations

Each observation's contribution to the parameters is **weighed by P(category | observation)**



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Maximization: Update each category's parameters based on the observations

New
$$\mu_{c} = x_{1}P(c|x_{1})+x_{2}P(c|x_{2})+...+x_{n}P(c|x_{n})$$

 $P(c|x_{1})+P(c|x_{2})+...+P(c|x_{n})$

- Think of each category as taking part of the responsibility for each observation
- That responsibility could be really big or small



Just like a weighted/soft version of computing category mean

GMM new mean

K-Means new mean

$$\frac{x_1 P(c | x_1) + x_2 P(c | x_2) + \dots + x_n P(c | x_n)}{P(c | x_1) + P(c | x_2) + \dots + P(c | x_n)} = \frac{0 * x_1 + 1 * x_2 + \dots + 1 * x_n}{0 + 1 + \dots + 1}$$

3000Hz

More expectation: do the same weighted estimates for the rest of the parameters

GMM Expectation-Maximization Initial After 1 iteration

Differences from k-means

Soft instead of hard categorization while learning

More parameters: prior probability of category, variance

- Guaranteed to increase likelihood of data given model at every step
- Could converge on local instead of global maximum

Multiple dimensions

Beyond just F2: can characterize vowels with F1 and F2 for 2-D Gaussian

+ more! (e.g. length)



image credit: wikipedia

Multiple dimensions

- Category means for each dimension $\mu = \begin{bmatrix} 0\\0 \end{bmatrix}$
- Instead of just σ^2 , covariance matrix

$$\begin{bmatrix} 1 & 3/5 \\ 3/5 & 2 \end{bmatrix}$$



Beyond vowels: Stop voicing

Voice Onset Time (VOT): pIn vs bIn



Stop voicing

Fundamental frequency (f0) also correlates with stop voicing! f0 is:

- rate at which vocal folds are vibrating
- associated with pitch

- Tend to have lower f0 right next to voiced stops
- Tend to have higher f0 right next to voiceless stops

Measuring f0





f0 and VOT in Korean stops

- Kirby (2013)
- Categories changing over time (ongoing!)

 Categories distinguished more and more by f0 than VOT

• Case of tonogenesis











"Agents"

- Have a memory of categorized observations $x_1 \dots x_n$
- Each observation has an f0 and VOT value
- Has a mixture of Gaussians model estimated from memory observations
- Adds each perceived observation to memory
- Memory observations decay over time



- "Agents"
 - Produce: sample from Gaussian mixture model
 - Sample a category from P(c)
 - Sample f0 and VOT values from P Gaussian distributions for that category:
 - $N_{VOT}(x | \mu_{VOT}, \Sigma)$ $N_{fO}(x | \mu_{fO}, \Sigma)$



- "Agents"
 - Perceive: receive observation with f0, VOT value
 - Categorize observation:
 - maximize P(c|x)
 - = P(c)P(x | μ_c, Σ)
 - Ideal observer?
 - P(c | x) = 0.6...

Add to memory





What makes distributions move?

Biases in production:

• Alter produced values

 λ: constant values added to one or more dimensions (f0, VOT)

β: chance of "enhancing" category distinction
 Move means further apart and reduce variance before sampling

Korean Simulations

- Initialize agent memories to 1960 distribution
- Run perception+production for many iterations
- Manipulate λ and β to eventually produce the 2000s distribution: what kind of bias and enhancement is necessary?

Evaluation

- How to compare simulation distribution to 2000s distribution?
- KL divergence: how much 'dirt' to move from one to the other



image source: Dibya Ghosh

Korean Simulations Findings

 Both enhancement and bias influences necessary to produce most 2000s-like distribution

 Other cues involved (spectral tilt, vowel length) - f0 takes over without any bias specifically preferring it